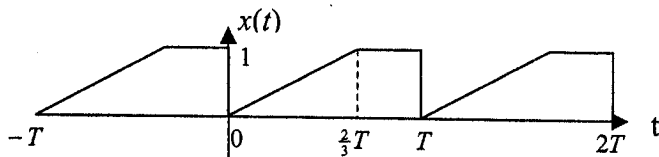


系所別: 電機工程學系 丙組 科目:

信號與系統

1. (A) (5%) Calculate the RMS (root mean-square) value of the periodical signal $x(t)$ shown in the figure shown below. (B) (2%) What is the RMS value of $x(7t)$? (C) (3%) What is the RMS value of $5x(-t)$?

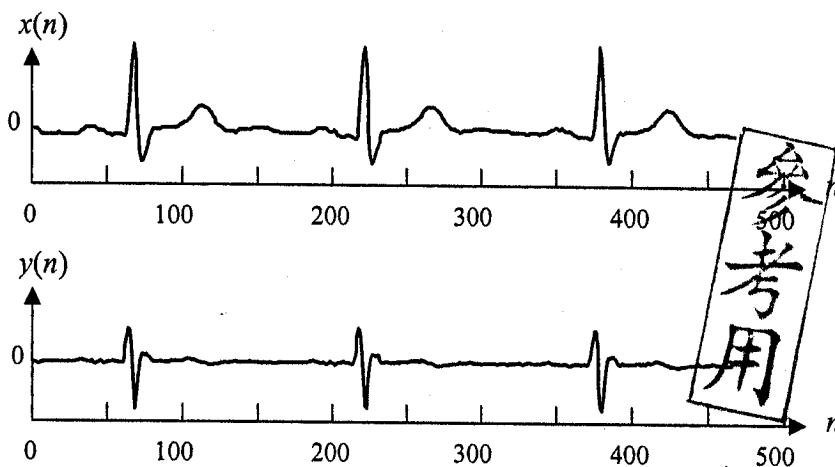


2. Let $x(n]$ and $y(n]$, whose waveforms are shown below, be the input and output, respectively, of a discrete-time LTI (linear time-invariant) system.

(A) (3%) Which of the following is the system function? (a) High-pass filtering (b) Low-pass filtering (c) All-pass filtering (d) Averaging (e) Integration.

(B) (2%) Which of the following equations best describes the relationship between the digital signals $x(n]$ and $y(n]$ shown below? (a) $y(n) = x(n) - x(n-1)$ (b) $y(n) - y(n-1) = x(n)$ (c) $y(n) = x(n) + x(n-1)$ (d) $y(n) + y(n-1) = x(n)$

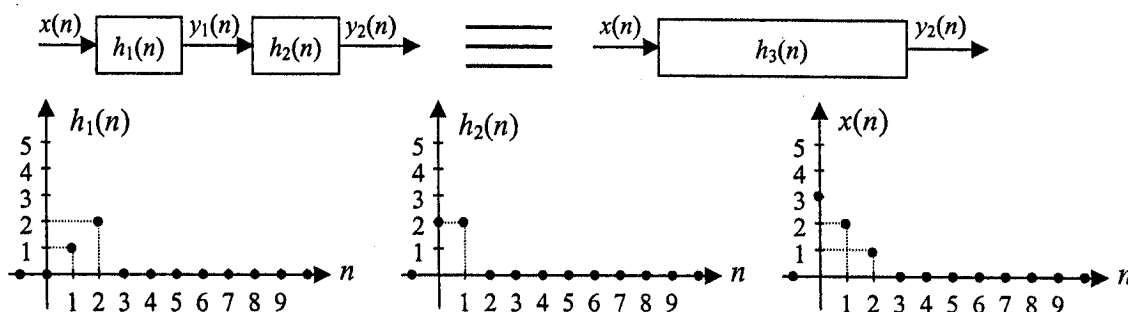
(C) (5%) Explain your answer to question (B).



3. Let $h_1(n]$ and $h_2(n]$ be the unit impulse responses of two LTI (linear time-invariant) systems. The two systems are connected as shown in the figure below. $x(n]$ is the input to the first system. The waveforms of $x(n]$, $h_1(n]$ and $h_2(n]$ are also shown below.

(A) (5%) Depict the waveforms of $y_1(n]$ and $y_2(n]$, the output signals of the two systems.

(B) (5%) Depict the waveform of $h_3(n]$, the equivalent system of the cascade of the first and the second systems.



注：背面有試題
忘

4. Calculate the Fourier Transforms $X(j\omega)$ of signal $x(t)$ and depict $X(j\omega)$.

(A) (5%) $x(t) = \begin{cases} 1, & |t| \leq T \\ 0, & |t| > T \end{cases}$

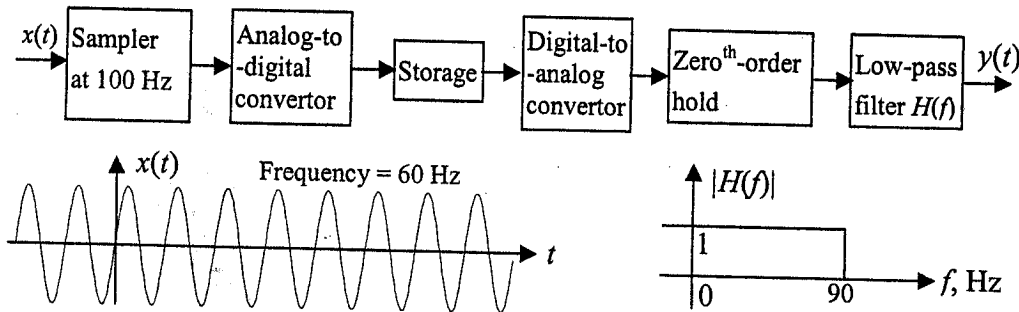
(B) (5%) $x(t) = \begin{cases} \cos(\omega_0 t), & |t| \leq T \\ 0, & |t| > T \end{cases}$ (Note: $\omega_0 = \frac{4\pi}{T}$)

5. (10%) Find the Inverse Fourier Transform of $X(j\omega) = \frac{-j\omega + 2}{(j\omega)^2 + 9j\omega + 20}$.

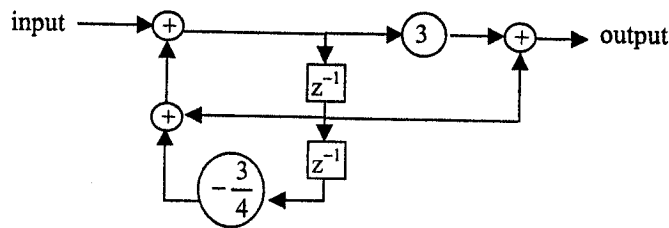
6. A junior engineer designs a system, as shown below, that is intended to store an analog signal in a digital form for later reconstruction. The first stage in the system is a sampler with a 100-Hz sampling rate (i.e., 100 samples per second). Both the analog-to-digital converter and the digital-to-analog converter in this system are nearly perfect. For the last stage in the system, he uses a low-pass filter with 90 Hz cutoff frequency, because he knows that the highest frequency in the input signal $x(t)$ is less than 90 Hz. The frequency response $H(f)$ of the low-pass filter is almost ideal. Now, he is testing his design with an 80-Hz sinusoidal signal as $x(t)$.

參考用

(A) (5%) What signal will he get in the reconstructed signal $y(t)$. (B) (5%) Explain why he will get such a signal. (C) (5%) How can the system be modified or changed in order to get correct reconstruction.



7. The signal-flow diagram of a digital filter is shown below. (A) (5%) Determine the transfer function of this filter. (B) (5%) Mark the poles and zero in the z-domain. (C) (5%) Find the difference-equation description of this filter. (D) (5%) Is this an FIR or an IIR filter? Why?



8. $H(s) = \frac{1}{s^2 + \sqrt{2}s + 1}$ is the characteristic of an analog low-pass filter.

(A) (5%) Calculate the -3 dB frequency.

(B) (5%) Express the phase response $\angle H(j\omega)$ as a function of ω , the angular frequency.

(C) (5%) Use bilinear transformation to design a digital filter $H(z)$ from $H(s)$. What is the transfer function $H(z)$?

(Bilinear transformation: $s = \frac{2z-1}{Tz+1}$, where T is the reciprocal of the sampling frequency.)