

國立中央大學九十一學年度碩士班研究生入學試題卷

所別：電機工程學系 兩組 科目：控制系統 共 / 頁 第 / 頁

1. Consider a system:

$$\begin{cases} \dot{x} = \begin{bmatrix} 0 & 1 \\ -8 & -6 \end{bmatrix}x + \begin{bmatrix} 0 \\ 8 \end{bmatrix}u \\ y = [2 \ 1]x \end{cases}$$

20%

Suppose that $x(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and $u = 2t u(t)$, where $u(t)$ = unit step function.

Find $y(t)$.

2. Consider a unit feedback system with the open-loop transfer function:

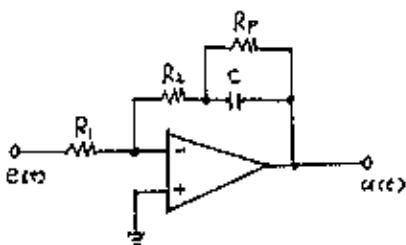
15%

$$\frac{s+2}{s(s+1)(s^2+2s+2)}$$

Find the gain margin.

3. Explain what kind of controller the following circuit is.

15%



Suppose $R_1 = R_2 = R_P = 1\text{M}\Omega$,
 $C = 1\mu\text{F}$.

4. A closed-loop system has the state equations

$$x(t) = \begin{bmatrix} -1 & 0 & 0 \\ 0 & 2 & 0 \\ -1 & -2 & -3 \end{bmatrix}x(t) + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}u(t)$$

$$y(t) = [1 \ 0 \ 0]x(t)$$

- (a) Calculate the system characteristic equation. (5%)
 (b) Use the results in (a) to determine system stability. (10%)

5. Given the compensator transfer function

$$G_c(s) = \frac{0.5s + 0.005}{s + 0.02}$$

- (a) Find the dc gain of the compensator. (7%)
 (b) Find the high-frequency gain of the compensator. (7%)
 (c) Is the compensator phase-lead or phase-lag. Why? (7%)

6. In the system of Figure 1, write state equations for the system such that $x_1(t)$ is the state for the upper block and $x_2(t)$ is the state for the lower block.

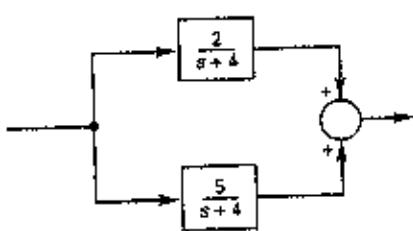


Figure 1

- (a) Determine if this system is controllable. (7%)
 (b) Determine if this system is observable. (7%)

參考用