## 國立中央大學八十八學年度碩士班研究生入學試題卷

共一頁 第一頁 應用數學 科目: 天文研究所 不分組

## PLEASE READ THIS SHORT MESSAGE FIRST:

Please work out the following problems in detail, otherwise put down how you may proceed. Attempt as many problems as you can but spend your time wisely. Please pay attention to the score of each problem. Good luck!

(1) (25 points)

The relations between the spherical coordinates  $(r, \theta, \phi)$  and Cartesian coordinates (x, y, z) are  $x = r \sin \theta \cos \phi$ ,  $y = r \sin \theta \sin \phi$ ,  $z = r \cos \theta$ .

- (a) Write down the Cartesian components of the unit vectors in the direction of increasing  $r_1$   $\theta$ and  $\phi$  (i.e.,  $\hat{e}_r$ ,  $\hat{e}_\theta$  and  $\hat{e}_\phi$ ).
- (b) The position vector of a particle is given by  $r\hat{e}_r$ . Find the velocity and acceleration of the particle in spherical coordinates. Identify the centripetal acceleration and the Coriolis
- (c) Compute  $\partial/\partial x$ ,  $\partial/\partial y$  and  $\partial/\partial z$  in spherical coordinates.
- (2) (25 points)

The adjoint of a matrix M is defined as the transpose of its complex conjugate and is denoted by  $M^{\dagger}$ . A matrix U is unitary if its inverse is equal to its adjoint, i.e.,  $U^{-1} = U^{\dagger}$ .

- (a) If  $\lambda$  is an eigenvalue of a unitary matrix, show that  $|\lambda| = 1$ .
- (b) Show that the eigenvectors corresponding to different eigenvalues of a unitary matrix are orthogonal.
- (c) Verify (a) and (b) by finding the eigenvalues and eigenvectors of the following matrix,

$$U = \frac{1}{\sqrt{2}} \left( \begin{smallmatrix} 1 & -1 \\ 1 & 1 \end{smallmatrix} \right) \,.$$

(3) (25 points)

The relation between the rate of change of a vector in an inertial frame and a rotating frame is

$$\left(\frac{\mathrm{d}\vec{S}}{\mathrm{d}t}\right)_{\mathrm{inertial}} = \left(\frac{\mathrm{d}\vec{S}}{\mathrm{d}t}\right)_{\mathrm{rotating}} + \vec{\Omega} \times \vec{S} ,$$

where  $\vec{\Omega}$  is the angular velocity of the rotating frame and is a constant. Solve  $\vec{S}$  in the rotating frame if  $\vec{\Omega} = \Omega \hat{e}_z$  and the rate of change in the inertial frame is a constant vector  $\vec{A} = A \hat{e}_y$ . [Hint: Let  $\vec{S} = \vec{S}' + (\vec{A} \times \vec{\Omega})/\Omega^2$ .]

(4) (25 points)

Define Fourier transform and its inverse as:

$$F(\omega) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} f(t) e^{i\omega t} dt, \qquad f(t) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} F(\omega) e^{-i\omega t} d\omega.$$

- (a) Find the Fourier transform of f(t), where f(t) = 1 if  $|t| \le a$  and f(t) = 0 if |t| > a. (b) Show the Parseval's relation:  $\int_{-\infty}^{\infty} f(t)\tilde{g}(t) dt = \int_{-\infty}^{\infty} F(\omega)\tilde{G}(\omega) d\omega$ , where the bar denotes complex conjugate.
- (c) Hence evaluate the integral  $\int_{-\infty}^{\infty} (\sin t/t)^2 dt$ .