

所別：機械工程學系碩士班 丁組(系統)(一般生)

科目：自動控制 共 2 頁 第 1 頁

機械工程學系光機電工程碩士班 甲組(機電系統控制)(一般生)

機械工程學系光機電工程碩士班 乙組(光機)(一般生)

本科考試可使用計算器，廠牌、功能不拘

*請在試卷答案卷(卡)內作答

1. (25 points) Consider the second order system shown in Figure 1, where ζ is a parameter of the system.

(a) (3%) Please find the closed-loop transfer function $G(s) = \frac{Y(s)}{R(s)}$.

(b) (5%) The closed-loop frequency response is expressed as $\frac{Y(j\omega)}{R(j\omega)} = Me^{j\phi}$.

Please find M and ϕ (in term of ω).

(c) (7%) Please find the critical damping ratio ζ_c . When $0 \leq \zeta \leq \zeta_c$, there exists the resonant phenomenon.

(d) (10%) When $\zeta = 0.5$, the maximum value of M_{max} occurs at the frequency ω_{max} . Please find M_{max} and ω_{max} .

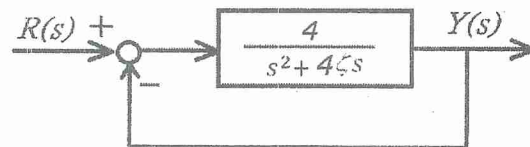
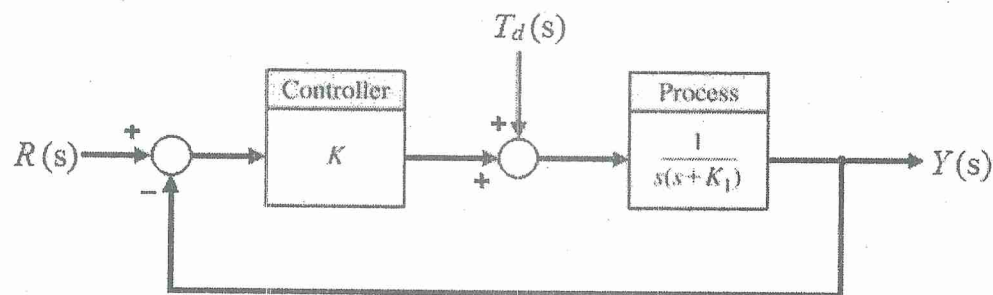


Figure 1. A second order system

2. (25 points) Consider the unity feedback system shown in the Figure. The system has two parameters, the controller gain K and the constant K_I in the process,

(a) (13 %) Calculate the sensitivity of the closed-loop transfer function to changes in K_I .

(b) (12 %) How would you select a value for K to minimize the effects of external disturbances $T_d(s)$



參考用

注意：背面有試題

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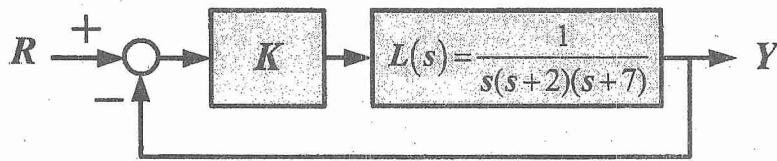
機械工程學系光機電工程碩士班 甲組(機電系統控制)(一般生)

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3. (25 pt) Consider the system.



- (6 pt) Please use Routh array to determine the range of K over which the system is stable.
- (7 pt) Please sketch the root locus of the system. Also find the asymptotes and break-away points.
- (6 pt) On the root locus, find the location and the gain, K , of the imaginary-axis crossing location.
- (6 pt) Please find the steady state error if input, R , is a ramp function (that is, $r(t) = t$ for $t \geq 0$).

4. 已知系統轉移函數如下

$$G(s) = \frac{K}{s^2 + as + b}, \quad K, a, b > 0$$

- (5 points) 常數 K 對根軌跡(Root locus)有何影響？
- (10 points) 常數 K 對波特(大小與相角)圖(Bode magnitude and phase)各有何影響？
- (5 points) 常數 K 對奈氏圖(Nyquist)有何影響？
- (5 points) 轉移函數從何而來，代表什麼，它的優點為何？

參考用

注意：背面有試題